The Complex Double Gaussian Distribution
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Abstract—We present the complex Double Gaussian distribution that describes the product of two independent, non-zero mean, complex Gaussian random variables, a doubly-infinite summation of terms. This distribution is useful in a wide array of problems. We discuss its application to blind TR detection systems by deriving the Neyman-Pearson optimal detector when the channel is modeled as the product of two independent complex Gaussian random variables, such as in a Time Reversal scenario. We show that near-optimal detection performance can be achieved with as few as 25 summation terms. Theoretical analysis and Monte Carlo simulations illustrate our results.

Index Terms—Complex Gaussian, Complex Double Gaussian, Detection, Time Reversal, Probability Distribution of Product of Gaussian Variables

I. INTRODUCTION

In [1], we presented the probability distribution function (PDF) for the product of two non-zero mean complex Gaussian random variables. We refer to it as the complex Double Gaussian PDF. This PDF is useful in many practical applications. The keyhole or pinhole channel model proposed in [2] describes a system where both the transmitter and the receiver are surrounded by multipath scattering and all communication between them passes through a single waveguide, such as the corner of a building. In this scenario, the channel is the product of two complex Gaussian random variables. In time reversal [3], a source first probes the channel, which is collected, time reversed (or phase conjugated), and retransmitted back to the original source. If this channel experiences Rayleigh fading, then the aggregate channel response is the product of two complex Gaussians. Finally, in many communication systems the received signal is sent through a linear combiner consisting built from a channel estimate generated from pilot symbols. Under Rayleigh fading, the output of this combiner is the product of complex Gaussian random variables. In all three of these scenarios, and many others, the complex Double Gaussian distribution can be a useful tool for design and analysis.

In this paper, we present the complex Double Gaussian PDF, which is computed via a doubly-infinite summation, whose terms include modified Bessel functions of the first and second kind. We also apply it to blind TR, see [4]. We use the complex Double Gaussian distribution to design the binary hypothesis test deriving the Neyman-Pearson optimal detector. We verify theoretically the performance of our detector using Monte Carlo simulations and compare its performance to an Energy Detector.

We present the PDF for the complex Double Gaussian distribution in Section II. The Blind TR Detection System is described in Section III, where we also derive the optimal detector. Simulation results are presented in Section IV, followed by our conclusion in Section V.

II. DOUBLE GAUSSIAN PDF

If $X \sim \mathcal{CN}(\nu_x e^{j\phi_x}, \sigma_x^2)$ (meaning that $X$ is a Complex Gaussian random variable with mean $\nu_x e^{j\phi_x}$ and variance $\sigma_x^2$) and $Y \sim \mathcal{CN}(\nu_y e^{j\phi_y}, \sigma_y^2)$ are independent random variables, then the product $Z = XY$ is characterized by the polar distribution:

$$f_{\theta_z, R_z}(\theta_z, r_z) = \frac{2 r_z}{\pi \sigma_x^2 \sigma_y^2} e^{-(k_x^2 + k_y^2)^2}$$

$$= \sum_{n=0}^{\infty} \frac{1}{n!} \left( \frac{\alpha}{2 \cos(\theta_z - \phi_x - \phi_y)} \right)^{n+1} K_{n+1}(\frac{2 r_z}{\sigma_x \sigma_y}) I_{n+1}(2 \alpha),$$

where:

$$\alpha = \sqrt{2 r_z k_x k_y \cos(\theta_z - \phi_x - \phi_y) / \sigma_x \sigma_y}$$

$$k_x = \frac{\nu_x}{\sigma_x}$$

$$k_y = \frac{\nu_y}{\sigma_y}$$

The detailed proof of (1) is exceedingly tedious. An abridged version of the proof is presented in [1], Appendix A. The proof begins by computing the joint distribution of the output phase $\Theta_z$ and input amplitudes $R_z$ and $R_x$. Then, a transformation of variables from $R_z$ and $R_y$ to $R_x$ and a dummy variable $T$ is conducted. Finally, the variable $T$ is integrated out. This integration process is extremely involved and requires the use of several Bessel Function identities and expansions found in [5], as well as several complicated integrations obtained using results in [6]. If the two inputs are both zero-mean ($\nu_x = \nu_y = 0$), then (1) reduces to [1]:

$$f_{R_z, \Theta_z}(r_z, \theta_z) = \frac{2 r_z}{\pi \sigma^2 \sigma_y^2} K_0 \left( \frac{2 r_z}{\sigma \sigma_y} \right).$$

Comments regarding (1): We call this result the complex Double Gaussian distribution and use the shorthand $\mathcal{CN}$ to refer to it:

$$Z \sim \mathcal{CN}(\nu_x e^{j\phi_x}, \sigma_x^2; \nu_y e^{j\phi_y}, \sigma_y^2)$$

The first two moments of (1) are given by:

$$E[Z] = E[X]E[Y] = \nu_x \nu_y e^{j(\phi_x + \phi_y)}$$

$$\text{Var}[Z] = \text{Var}[X] \text{Var}[Y] = \sigma_x^2 \sigma_y^2.$$

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Likewise, higher order moments of $Z$ are obtained from the first two moments of $X$ and $Y$.

The infinite summations over $n$ and $p$ arise from the Rician k-factors $k_x$ and $k_y$, respectively. These terms express the relative strength of the deterministic components of $X$ and $Y$. If one of $k_x$ or $k_y$ is zero, the corresponding sum across $n$ or $p$, respectively, becomes superfluous and the PDF reduces to a single summation. If both are zero, then the summation in (1) reduces to a single term.

We plot an example of (1) in Figure 1 for the case where $k_x = 1, k_y = 1/\sqrt{2}$, $\sigma_x^2 = 1, \sigma_y^2 = 1/2$, and $\phi_x = \phi_y = \pi/2$. This plot was generated using 100 summation terms ($n = 0, \ldots, 9, p = 0, \ldots, 9$). The plot exhibits a cardioid shape, this is because we are plotting the polar form of the two-dimensional PDF $f_{R_x, \phi_x, (r_x, \theta_x)}$. A simple conversion to Cartesian coordinates would remove the hole that appears at the origin.

III. BLIND TIME REVERSAL DETECTION

We consider the detection of a target in the presence of stationary random multipath scattering, this application is briefly discussed in the recently submitted manuscript [1], but we present here a more in-depth analysis. We will utilize a Time Reversal detection strategy similar to the one outlined in [3], [4] with one notable difference. In the detection system we consider here, the Time Reversal mirror will not communicate with the detector. Thus, the detection system must operate without knowledge of the result of the forward transmission. The meaning of this statement will be clarified below.

We define the frequency samples $\omega_q, q = [0, Q - 1]$. We model the target as a point target with a deterministic response $T$. For the clutter, we utilize the Wise-Sense Stationary Uncorrelated Scattering (WSSUS) model for multipath propagation [7]. WSSUS assumes that the multipath response comes from a linear superposition of uncorrelated echoes, and that each echo is characterized by a WSS impulse response.

From this, it follows that the clutter is drawn from a zero-mean complex Gaussian distribution with power spectral density (PSD) $P_c(\omega_q)$. This channel model is discussed in detail in [8] and was used in [4]. We transmit the probing signal $S(\omega_q)$ and write the response:

$$Y(\omega_q) = [T + C(\omega_q)] S(\omega_q) + V(\omega_q), \quad (9)$$

where $C(\omega_q) \sim \mathcal{CN}(0, P_c(\omega_q))$ is the clutter response, and $V(\omega_q) \sim \mathcal{CN}(0, \sigma_v^2)$ represents additive noise. For simplicity, we use a white probing signal:

$$S(\omega_q) = \sqrt{E_s}/Q, \quad (10)$$

for some transmit power $E_s$. The Time Reversal probing signal is generated using a scaled, phase-conjugated version of the received signal $Y(\omega_q)$:

$$S_{TR}(\omega_q) = kY^*(\omega_q), \quad (11)$$

where $k$ is the energy normalization factor defined by:

$$k = \sqrt{\frac{E_s}{\sum_{q=0}^{Q-1} |Y(\omega_q)|^2}}. \quad (12)$$

We assume that $k$ is approximately deterministic, as was argued in [9]. The Time Reversal probing signal $S_{TR}(\omega_q)$ is distributed as a complex Gaussian:

$$S_{TR}(\omega_q) \sim \mathcal{CN}(kt^*, k^2 (P_c(\omega_q)E_s/Q + \sigma_v^2)). \quad (13)$$

The signal $S_{TR}(\omega_q)$ is then transmitted from the receiver back to the source, where the received signal is:

$$Y_{TR}(\omega_q) = (T + \overline{C}(\omega_q)) S_{TR}(\omega_q) + \overline{V}(\omega_q), \quad (14)$$

where $\overline{C}(\omega_q)$ is the clutter channel for the second transmission, and $\overline{V}(\omega_q)$ is the noise signal for the second transmission. We assume that the clutter and noise signals are independent of each other and independent from one transmission to the next. This assumption will be valid if there is sufficient time delay between the forward and TR transmission stages, relative to the coherence time of the clutter channel. If we ignore the noise term, then (14) is distributed according to the product of independent Complex Gaussians:

$$Y_{TR}(\omega_q) \sim \mathcal{CN}(\mu_{x,q}, \sigma_{x,q}^2; \mu_{y,q}, \sigma_{y,q}^2), \quad (15)$$

$$\mu_{x,q} = T,$$

$$\mu_{y,q} = kT^*,$$

$$\sigma_{x,q}^2 = P_c(\omega_q),$$

$$\sigma_{y,q}^2 = k^2 (P_c(\omega_q)E_s/Q + \sigma_v^2).$$

At this stage, we set up the binary hypothesis test. The detectors in [3] were designed to use both $Y(\omega_q)$ and $Y_{TR}(\omega_q)$. In this application, however, we consider the case where $Y(\omega_q)$ is not available to the detector. In the null hypothesis, the case where no target is present, $T = 0$, and $Y_{TR}(\omega_q)$ is distributed according to (5). In the alternative hypothesis, $T > 0$, and $Y_{TR}(\omega_q)$ is distributed according to (1). Thus:

$$\mathbb{H}_0: \quad \mu_{x,q} = 0, \quad \mu_{y,q} = 0$$

$$\mathbb{H}_1: \quad \mu_{x,q} = T, \quad \mu_{y,q} = kT^* \quad (16)$$
A. Likelihood Ratio Test

To compute the likelihood ratio test statistic, we utilize the mean and variance parameters given in (15). We divide the distribution under $\mathbb{H}_1$, given by (1), by the distribution under $\mathbb{H}_0$, given by (5). The result is given:

$$\ell_q = \prod_{q=0}^{Q-1} e^{-\left(k_{x,q}+k_{y,q}\right)} \sum_{n,p=0}^{N-1} \frac{1}{n!p!} \left( \frac{\alpha}{2 \cos(\theta_q)} \right)^{n+p}$$

$$\left( \frac{k_{x,q}}{k_{y,q}} \right)^{n-p} K_{n-p} \left( \frac{2r}{\sigma_{x,q}\sigma_{y,q}} \right) \frac{K_0}{\sqrt{2\pi r}} I_{n+p} (2\alpha),$$

where $\theta_q = \angle Y_{TR}(\omega_q)$, $r_q = |Y_{TR}(\omega_q)|$, and $\alpha_q = \sqrt{2r_q k_{x,q} k_{y,q} \cos(\theta_q) / \sigma_{x,q} \sigma_{y,q}}$. The summations over $n$ and $p$ are both carried out for the first $N$ terms, instead of to $\infty$, resulting in a total of $N^2$ summation terms. Unless otherwise specified, we will utilize $N = 15$ in our simulations. It would be possible to construct the likelihood ratio $\ell$ numerically, through a Monte Carlo simulation, but that approach would be much more computationally complex, and would not yield the analytical representation in (17). From the likelihood ratio $\ell$, we can construct the test [10]:

$$\phi = \begin{cases} 1 & \ell \geq \ell_0 \\ 0 & \ell < \ell_0 \end{cases},$$

for some threshold $\ell_0$. Ideally, we would use the distribution of the test statistic $\ell$ to determine the appropriate threshold $\ell_0$ for some desired false alarm rate. However, its distribution is unknown, so we must rely on Monte Carlo simulations to determine the appropriate threshold.

IV. MONTE CARLO SIMULATIONS

To test the detector derived in Section III, we construct a simulation scenario wherein the clutter channel follows a Gaussian power spectral density in the band 2-4GHz, and the target (a point target) has a constant value $T = e^{j \pi /2}$. We confine our transmit power to the $E_x = 1$, and vary the total clutter power $E_c = \sum_{q=0}^{Q-1} P_c(\omega_q)$. We vary the number of frequency samples $Q$ and conduct $MC = 10^6$ Monte Carlo trials for each scenario.

Using these Monte Carlo trials, we set the probability of false alarm to $(P_{FA}) = 0.01$, determine the appropriate threshold from a noise-only simulation, and then use that threshold to compute the probability of detection ($P_D$) for the likelihood ratio test given in (18) as we vary the number of frequencies $Q$ and the signal-to-noise ratio $SNR$. The signal-to-noise ratio is defined:

$$SNR_{DB} = 10 \log_{10} \left( \frac{E_x |T|^2}{Q \sigma_T^2} \right).$$

We also define the signal-to-clutter ratio $SCR_{DB}$:

$$SCR_{DB} = 10 \log_{10} \left( \frac{Q |T|^2}{\sum_{q=0}^{Q-1} P_c(\omega_q)} \right).$$

For comparison, we also computed the receiver operating characteristics of an energy detector:

$$\ell_{ED} = \sum_{q=0}^{Q-1} |Y_{TR}(\omega_q)|^2. \quad (21)$$

For the first test, we compare the likelihood ratio test (LRT) that we derived in (17) to the Energy Detector in (21) with varying $SNR$. We plot the results in Figure 2, which depicts Probability of Detection for each scenario against $SNR_{DB}$. We consider two scenarios: strong clutter ($SCR_{DB} = 0$) and weak clutter ($SCR_{DB} = 5$). In the strong clutter case, the ED fails to distinguish the target, while the LRT achieves $P_D > .9$ at high SNR. In the weak clutter case, the ED improves and
performs similarly to the LRT detector in strong clutter. The LRT improves as well, outpacing the ED. From this test, we can see that the LRT has a distinct SCR advantage over the ED, since it utilizes the distribution of $Y_{TR}(\omega_q)$.

For the second test, we set the signal-to-clutter ratio to a fixed value of $SCR_{dB} = 0$ and the signal-to-noise ratio to a fixed value of $SNR_{dB} = 0$. We allow the number of frequencies $Q$ to take on the values $Q = 10$, $20$, $50$, and $100$. The results are plotted in Figure 3, on a log-log scale with probability of detection ($P_D$) ranging from $0.1$ to $1$ and probability of false alarm ($P_{FA}$) ranging from $10^{-3}$ to $1$. From this plot, we can see that the LRT performance increases notably with increasing $Q$, while the ED improves marginally by comparison. For example, if we set the false alarm rate to $P_{FA} = 10^{-2}$, the ED will achieve $\approx 15\%$ detection with $Q = 10$ and $20\%$ detection with $Q = 100$, a $33\%$ increase. The LRT, however, achieves $\approx 50\%$ detection with $Q = 10$ and almost $80\%$ with $Q = 100$, a $60\%$ increase. Since the LRT is leveraging more information about the channel and target, it stands to benefit more from a larger sampling space.

### V. Discussion and Conclusion

We present the complex Double Gaussian distribution, a recently derived result. In this paper, we show the usefulness of this distribution by applying it to the problem of a Blind TR Detection scheme. We use this distribution to characterize the aggregate channel response and derive the optimal detector in a Neyman-Pearson sense. We verify our results with Monte Carlo simulations and compare them to an energy detector. We also show that near-optimal detection performance can be achieved with as few as 25 terms from the doubly infinite summation that makes up the likelihood ratio test statistic. In addition to the application that we present here, an important problem that can benefit from the complex Double Gaussian distribution is error analysis in communication systems that rely on a linear combiner, such as M-ary Phase Shift Keying (M-PSK) systems [11]. The output of the linear combiner can be characterized as the product of two complex Gaussian random variables. This allows the complex Double Gaussian distribution to be used for analysis, such as computing the Symbol Error Probability (SEP). This problem was considered in detail in [1].

### REFERENCES


